Anthropogenic boat noise reduces feeding success in winter flounder larvae

(Pseudopleuronectes americanus)

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Abstract

The aim of this study was to explore an emerging discipline addressing the impact of anthropogenic noise on larval stages of marine organisms. We assessed the influence of boat noise on the feeding behaviour of the pelagic larvae of winter flounder (*Pseudopleuronectes americanus*, Walbaum 1792). The hypothesis was that boat noise influences the feeding behaviour of *P. americanus* flounder larvae independently of prey density. Aquaria containing *P. americanus* larvae were placed in water baths in which boat noise was diffused for the "noise" treatment and compared to control aquaria with no sound emissions. Larvae were filmed using cameras placed above the aquaria and their behaviour was recorded. Larvae exposed to anthropogenic noise displayed significantly fewer hunting events than controls, and their stomach volumes were significantly smaller. This noise effect was the same at all prey densities used, suggesting that larval feeding behaviour is negatively impaired by anthropogenic noise.

Keywords: Feeding behaviour, winter flounder, larvae, anthropogenic noise, vessel noise

Introduction

Ambient underwater sound in the aquatic environment is used by marine organisms for orientation, communication among individuals, predator avoidance, and prey detection, and it can also be used as a larval settlement cue in various species, especially among those residing in coastal areas (Montgomery et al. 2006; Götz et al. 2009; Slabbekoorn et al. 2010; Stanley et al. 2010). However, anthropogenic underwater noise resulting from increasing maritime navigation, offshore wind and tidal turbines, mariculture facilities, piling installations, and seismic surveys for oil and gas exploration can have detrimental impacts on many marine organisms (Southall et al. 2007; Popper and Hastings 2009; Slabbekoorn et al., 2010; Popper et al. 2014; Kunc et al. 2016; Cox et al. 2018). These negative effects will likely increase since anthropogenic noise levels are rising with increasing human activities (Williams et al. 2015). Studies on the effects of noise on foraging have been done with different life stages and different fish species, but studying larval stages is of special interest (high sensitivity to abiotic factors; the importance of larval survival in population recruitment) and poses specific challenges. Larval marine organisms have been shown to be sensitive to aquatic noise. Invertebrate larvae can detect and respond to aquatic noise (Simpson et al. 2011). Using the aquatic larval stage of damselfly, a freshwater invertebrate feeding on Daphnia during this aquatic phase, Villabolos-Jimenez et al. (2017) obtained results suggesting that underwater noise may decrease feeding. Anthropogenic noise may cause malformations or delays in development (seismic pulses, Aguilar de Soto et al. 2013; boat traffic noise,

 Nedelec et al. 2014) as well as damage to sensory epithelia (sinusoidal wave sweeps, Solé
et al. 2016).
In larvae from four damselfish species (*Pomacentrus amboinensis*, *P. brachialis*, *P.*

moluccensis, P. nagasakiensis), Simpson et al. (2010) showed that orientation behaviour is influenced by recent acoustic experience, i.e., reef noise. Positive orientation behaviour in response to reef noise was also found in larvae of longspine cardinalfish (Apogon doryssa) (Holles et al. 2013), but these authors showed that boat noise can disrupt this behaviour. In Atlantic cod (Gadus morhua) larvae, the increased rate of ship noise playbacks as well as "regular" ship noise caused a reduction in growth, while yolk sac resorption was more rapid in the presence of "regular" noise (Nedelec et al. 2015). More recently, Fakan and McCormick (2019) showed an increased heart rate during embryogenesis in cinnamon clownfish (Amphiprion melanopus) and spiny chromis (Acanthochromis polyacanthus) exposed to boat noise. This study also clearly demonstrated that the effects of noise are species-specific.

In marine fishes, the larval stage is critical in terms of survival and is recognized as being the main source of variability in the annual recruitment of feral populations (Houde 2016). Many factors determine larval survival rate including feeding success (Fortier and Harris 1989; Robert et al. 2008), and aquaculture-related studies have shown that transition to exogenous feeding once vitelline reserves are depleted seems to be particularly critical (e.g., Øie et al. 2017).

Here, we used winter flounder, *Pseudopleuronectes americanus*, a species for which reproduction and larval feeding are well understood (Audet and Tremblay 2011) to

determine how motorized boat noise combined with prey density would affect feeding success during this critical stage. We hypothesized that anthropogenic vessel noise would impair feeding success during feeding on live prey and that this effect would be more pronounced with lower prey availability. Winter flounder is a dominant benthic species in the St. Lawrence estuary (Bigelow and Schroeder 1953; Pereira et al. 1999) and is present in areas where a local rise in ambient noise levels has been noted (Gervaise et al. 2012). Winter flounder sport fishing is economically important in North America (Fairchild 2008; Fishwatch 2019), including Québec (DFO, 2012). However, over the last few decades, most populations including that of the St. Lawrence estuary have encountered marked decreases for reasons that remain to be identified. Conservation issues thus require research efforts on all factors that may affect recruitment. Like many marine vertebrates, P. americanus has a complex life cycle. Upon hatching, larvae are pelagic until they undergo metamorphosis to the juvenile stage (Pereira et al. 1999). During this pelagic larval phase, feeding success is vital for growth and for accumulating enough energy for successful metamorphosis. Larvae are visual feeders and spend most of the critical periods of their development in shallow coastal areas, which are especially vulnerable to boat noise. Thus, this species is likely a good model to assess the impact of anthropogenic noise on marine species that use coastal areas during critical stages of their life history.

Material and methods

 Larval production

Mature P. americanus females were captured in the Baie des Chaleurs offshore of Bonaventure (OC, Canada) during the breeding season and brought to the Station aquicole de l'ISMER (Rimouski, QC, Canada; 48° 31' N; 68° 28' W). Fertile males were available at the wet lab facility. Egg fertilization and incubation were done according to the method described by Vagner et al. (2013). Upon hatching, larvae were reared according to the standard procedures used in our laboratory (Vagner et al. 2013; Martinez-Silva et al. 2018). Briefly, larvae were transferred into 55 L cylindro-conical fiberglass tanks and reared in green water at 10°C with a 12h:12h L:D photoperiod. Larval density was set to 1 larva ml⁻¹, gentle aeration was used to create upwelling, and a constant flow of filtered (1 μm) seawater was provided. In larval rearing tanks, the water supply was stopped each day for 12 h while a green water preparation (Nannochloropsis oculata at 1.6×10⁶ cells L⁻¹) was added to each tank. At the end of the day, water circulation was restored, allowing complete renewal of the tank water overnight. Larvae were routinely co-fed with rotifers, *Brachionus* plicatilis, and a commercial diet (GEMMA Wean 0.3, SKRETTING, France) was added to their regime once they reached 5.5 mm (Ben Khemis et al. 2003; Vagner et al. 2013; Martinez-Silva et al. 2018).

Underwater sound

As described in Jolivet et al. (2016), the vessel noise emitted during the experiments was initially recorded at a mussel aquaculture site at St. Peter's Bay on Prince Edward Island

(Canada; 46° 25.963' N; 62° 39.914' W). The calibrated hydrophone (High Tech, Inc., Mississippi, USA, HTI-99-HF: sensitivity −169.7 dB re 1 V/μ Pa; frequency range 2 Hz to 125 kHz flat response) was placed 25 cm from the bottom, near the anchor of the mussel line, and connected to an underwater acoustic recorder (RTSYS-Marine Technologies, France, EA-SDA14, 156 kHz, 24-bit resolution). The farmer's boat (11 m in length; D & H Boatbuilding hull with diesel motor, Cummins 300 hp C series) passed three times above the recording hydrophone during calm natural conditions characterized by a wave height of 0.2 m and wind speed of 3.8 m s⁻¹ (http://climat.meteo.gc.ca/). From the recording, a sequence lasting 30 s that corresponded to the maximum vessel noise sound intensity was selected using customized codes written in MATLAB (The MathWorks, Inc.) software.

Experimental design

For the experiments, four 40 L aquaria were used, each containing 30 L of water. A rectangular 2 L glass container was placed on a platform 19.5 cm from the aquarium's bottom so that the upper rim of the aquarium was 1 cm above the water's surface (Fig. 1). Water temperature in the aquaria was constant and monitored by probes (Onset Hobo Water Temp Pro V2 Data logger U22-001); the average temperature was $12.1 \pm 0.4^{\circ}$ C with a mean increase of $1.2 \pm 0.2^{\circ}$ C between the start and the end of experiments (2 h). Lowintensity lights were installed above each aquarium to reproduce a light intensity present in the production room (around 400 lux).

Twenty experimental larvae were randomly sampled in the water column of the rearing tank prior to the morning feeding, which occurred when the lights were turned on in the production room. Larvae were transferred into the 2 L containers (1.8 L of water) to acclimate for 1 h prior to the start of the experiment and were not fed during the acclimation to ensure feeding during the experiment. No boat noise was played during the acclimation period. A digital camera (GoPro, Hero+ LCD CHDHB-401) fitted with a macro filter (Polar Pro, macro filter 15-06746) was installed above each aquarium to record larval behaviour for 2 h following the acclimation period (Fig. 1).

For each experimental trial, larval behaviour was monitored simultaneously in the presence or absence of vessel noise; there were two aquaria per treatment and four experimental trials were carried out. Individual larval behaviour was then monitored for 20 larvae × two aquaria × four trials, for a total of 160 larvae in the presence of boat noise and 160 larvae with no noise. Larvae could not see the sound source because the bottom of the aquarium was opaque to facilitate their tracking. In the experimental tanks, larvae were only offered rotifers, with no commercial diet. Prey density was low in the first trial (5 \pm 0.6 rotifers ml⁻¹), medium in the second and third trials (11 \pm 2.0 rotifers ml⁻¹), and high in the fourth trial (14 \pm 0.8 rotifers ml⁻¹). The low and medium densities correspond to prey densities previously used with success along with co-feeding with commercial diet (Vagner et al. 2013; Martinez-Silva et al. 2018).

Sound emissions

Waterproof speakers (AQUA 30, DNH, 8 ohms, 80–20,000 Hz), plugged to an amplifier (Plug & Play 12 W) and connected to a PC, were installed in two of the four aquaria to continuously replay the vessel noise. The sound emission under experimental conditions was calibrated using a calibrated hydrophone (HTI-96 MIN; High Tech, Inc.) associated with a digital recorder (Song Meter SM2+; Wildlife Acoustics). The source was placed in the center of the aquarium just below the glass container. The multiple reflections off the sides of the aquaria produced homogeneous sound conditions (S.E.: \pm 1.5 dB) in the glass container, which was confirmed by sound measurements performed in each corner and the center prior the experiment. A correction function was calculated from 30 s recordings of calibrated sound done in each corner and the center, and this was applied to the vessel noise to replicate the *in situ* spectrum of the vessel noise as nearly as possible. By varying the gain of the amplifier, the intensity was adjusted to match natural conditions (sound level [SL]: 130 dB re 1μ Pa² between 100 and 10,000 Hz). Two recordings were also made in adjacent basins to check the "silent" conditions (located 1.5 m away).

Rotifer production and counts

 Rotifers were reared in an 18 L tank and fed with Selco® S.parkle (INVE Aquaculture Ltd., Thailand) four times a day. The culture concentration was estimated every morning, and the volume of culture needed to reach a given prey concentration in each experimental aquarium was calculated.

After the 1 h acclimation period, the video recording was started, rotifers (prey) were added to each experimental aquarium, and seawater was added to top-up each aquarium to 2 L. At the end of the experiments, subsamples of rotifer cultures and seawater from each aquarium were filtered through a 10 µm sieve and preserved in 95% ethanol for prey concentration assessment. Rotifer concentration was estimated both before and after the experiments by diluting the filtered rotifer samples in 80 ml of ethanol and counting rotifers in 3 ml aliquots under a binocular microscope (three aliquots per sample).

Behaviour analysis

 The videos were analyzed using Noldus Observer XT 9.0 software (Noldus Information Technology Inc., Leesburg, VA, USA). A delimited field covering 95% of the aquarium's bottom but avoiding sides and corners, where visibility was impaired, was used to analyze the videos. Only larvae found within this delimited field were considered. A period of 12 minutes, always from minute 12 to 24 of the 2 h video for standardization purposes, was analyzed for occurrence frequencies and duration of each behavioural trait (in seconds) for each replicate and for each larva present in the observation field, giving a total of 132 larvae in the absence and 117 in the presence of boat noise. The various observed and recorded behaviours were set to be mutually exclusive state events except for hunting, which was considered as a point event. The following behaviours were recorded: (1) Hunting: larva moves rapidly with a wiggling movement; (2) Swimming: larva moves around actively in the water column; (3) Resting: larva undertakes no active movement but rather stays

motionless on the bottom or floats passively; (4) Out: larva swims out of the observation field. Morphometric measurements At the end of each experiment, all larvae were recovered and sacrificed by prolonged anaesthesia in MS 222. A side-view photo was taken using a digital camera (Evolution VF, Media Cybernetics) fixed on a binocular microscope at 20X magnification (Olympus SZ61 model SZ2-ST; Olympus Corporation, Tokyo, Japan) that was connected to a personal computer (Fig. 2). A cold light source (NCL 150; Volpi, USA) was used to illuminate specimens. For each individual, fork length (FL) and eye diameter (to check whether larvae were of similar sizes) as well as stomach height, length, and surface area were measured on each photo using image processing software (Image-Pro Express 5.1.0.12; Media Cybernetics, Inc., USA). Stomach volume was calculated under the rough assumption of cylindrical shape ($V = \pi h r^2$; h = stomach height; r = stomach radius). Statistical analysis To compare larvae at the same stage of development, it was necessary to do experiments

within a short period of time, which limited the number of trials that could be run. This precluded the use of test aquarium as the statistical unit because there were relatively few trials and thus low statistical power. However, the large volume of the experimental system vs. the size of larvae was such that interactions between larvae were avoided. The video analysis of 20 larvae per aquarium showed that larvae had no gregarious behaviour, and no behavioural interactions were observed among individuals. For these reasons, larvae were used as the statistical unit. Analyses were performed using STATISTICA software (STATISTICA 6.1, StatSoft Inc., France). Normality and homoscedasticity were verified using Kolmogorov-Smirnov and Levene tests, respectively (α =0.05). Two-way nested ANOVAs (replicate aquaria nested in the "noise" factor) were used to determine significant differences in larval feeding and swimming behaviour as a function of the presence or absence of boat noise and prey concentration (low, medium, high). Because no significant replicate effect was found for any of the variables tested ("aquarium" nested in "boat noise"; p > 0.05 for all variables considered), two-way ANOVAs testing interactions between factors (boat noise × prey density) were run. When significant factor effects were found, a posteriori Tukey comparison of means tests (α = 0.05) were used.

Results

Underwater sound recording

 The replayed vessel noise in the two aquaria was homogenous, with 129 and 127 dB re 1µPa² between 100 and 1,000 Hz corresponding to the *in situ* recorded source signal (Table 1, Fig. 3; aquaria 3 and 4). The sound levels measured in the two aquaria under control conditions differed from the other two (Table 1, Fig. 3; aquaria 1 and 2). The sound

levels in the aquaria with no sound treatment were slightly higher than the conditions before the experiments (Table 1) but remained consistent with natural conditions as defined by Wenz's formula (Wenz 1962) (Fig. 3).

Predation analysis

Even though we used larvae of the same age, fork length and eye diameter differed slightly among treatments (Fig. 4a, b). There was a significant boat noise \times prey density effect ($F_{2,312}=3.65, p=0.027$) on larval fork length. However, the *a posteriori* test failed to find a significant difference among treatments, and the overall mean larval fork length (\pm S.D.) was 4.77 \pm 0.515 mm. A significant boat noise \times prey density effect ($F_{2,312}=4.09, p=0.018$) was also observed for eye diameter (Fig. 4b): larvae with the smallest eyes were from the low prey density/absence of boat noise combination. As stated above, nested ANOVA failed to indicate any differences between replicate aquaria for each experiment, and this was also the case for fork length and eye diameter.

The variation in prey concentration had no effect on the hunting behaviour ($F_{2, 243} = 1.28$, p = 0.28) while hunting attempts were 34% less frequent in the presence of sound compared to the treatment when sound treatment was absent ($F_{1, 243} = 6.75$, p = 0.010; Fig. 5a). There was no interaction between prey concentration and sound treatment ($F_{2, 243} = 1.71$, p = 0.18) on the number of hunts. Stomach volume measurements (Fig. 5b) showed that stomachs were 13% smaller in the presence of boat noise ($F_{1, 312} = 4.29$, p = 0.039),

and this effect was independent of prey density (boat noise \times prey density, $F_{2,312} = 0.488$,

p = 0.614).

Prey concentration significantly influenced some of the measured variables, but without interaction effects with the presence or absence of boat noise. There was a significant effect of prey density on the proportion of time the larvae spent swimming ($F_{2, 243} = 3.36$, p = 0.036; Fig. 5c), but sound treatment had no effect (boat noise: $F_{1, 243} = 0.32$, p = 0.57; boat noise × prey density, $F_{2, 243} = 0.74$, p = 0.48). Globally, larvae swam $66 \pm 38.2\%$ of their time. Larvae seemed to spend less time swimming when prey concentration was intermediate, but these differences were not significant according to post-hoc analyses (Fig. 5a). However, stomach volume (Fig. 5b) was significantly larger when prey concentration was intermediate (Prey density: $F_{2, 312} = 3.67$, p = 0.026). There was no significant prey concentration × boat noise interactions ($F_{2, 312} = 0.488$, p = 0.61).

Discussion

 The presence of boat noise had a significant effect on the hunting behaviour of *P. americanus* larvae. Larvae exposed to boat noise spent less time hunting and had smaller stomach volumes compared to those with no sound treatment. This suggests that more preys were consumed in the absence of boat noise.

In adult fish, noise has been shown to affect predation. Purser and Radford (2011) noted a decrease in foraging performance in three-spined stickleback (*Gasterosteus aculeatus* L. 1758) exposed to noise; this decrease resulted from (1) the misidentification of food versus

non-food items, as shown by an increased number of attacks on the latter, and (2) fewer successful attacks on food items under noisy conditions.

In the present study, the impact of boat noise emission compared to control conditions on larvae was evident, decreasing the number of attacks as well as larval stomach volume, suggesting that many of the observed hunting attempts were not successful. Such differences between the sound treatments cannot be attributed to development since larval fork length was similar among treatments and there were no consistent differences in eye diameter between control and noisy conditions (larvae are visual predators). Indeed, larvae with the less developed eyes (smaller eye diameter) were observed in the "low prey density/absence of boat noise" experimental combination, which showed no difference with other combinations related to boat noise regarding hunting events or stomach volume. Because the distribution of wild winter flounder larvae is not known in the St-Lawrence estuary, we could not work with wild larvae. Our larvae were reared in our wet lab facilities and so were exposed to the wet lab's soundscape in rearing tanks. In the natural environment, the signal-to-noise ratio (SNR) between boat noise and ambient noise was 3. During our experiments, the SNR calculated in aquarium 3 between received boat noise and ambient noise before the experiment is 5.5. Finally, the calculated SNR between the boat noise received in aquarium 3 and the "silent" aquarium 1 at the same time was 4.5. Voellmy et al. (2014) tested the effects of acoustic noise on adult Gasterosteus aculeatus and European minnow (*Phoxinus phoxinus*). These authors obtained similar results in that fewer hunting strikes were made by both sympatric species. However, the way in which foraging success was reduced differed: G. aculeatus made more foraging errors whereas

 P. phoxinus showed a decrease in foraging efforts. The latter corresponds to the behaviours observed in *P. americanus* larvae, which, as Purser and Radford (2011) suggested, may be related to a shift in attention. Luo et al. (2015) proposed three ways by which noise pollution can affect fish foraging: acoustic masking, reduction of attention, and noise avoidance behaviours. Unfortunately, the present experiment did not allow us to evaluate the presence of acoustic masking or avoidance behaviours. It should be emphasized that in contrast to studies using juveniles or adult fishes, we used larvae that are still early in their development. They do not school, they are very poor swimmers, and drift with currents. Moreover, no interactions among individuals were observed.

Since all larvae had their last feeding the night before the experiment and were of similar size, the observed variation in stomach volume supports the conclusion that larvae had a higher feeding success in the absence of boat noise. Licois (2006) confirmed that starving *P. americanus* juveniles (6.4 to 12.2 mm in total length) for 16 h was sufficient to eliminate prey from the digestive system. This supports our assumptions that larva digestive systems were empty at the start of experiments. Furthermore, larvae are transparent at this stage of development, therefore the opaque stomach area observed at the end of the experiment indicated the ingestion of prey and could be easily determined.

The differences in stomach size indicate that feeding success was better at the intermediate and high prey densities compared to the low prey density. The results related to swimming budget seem to indicate that less time swimming and large stomachs were associated, which could be related to a higher probability of predator–prey encounters when prey were more abundant. Nevertheless, in the absence of significant comparisons

 between density treatments, it would be too speculative to provide further explanations. Because prey concentration had no effect on the occurrence of hunting events, it may be argued that the lowest prey concentration was sufficient to fulfill larval needs. Laurence (1977) determined that the critical prey concentration needed for P. americanus larvae to meet growth and metabolic energy requirements is around 0.6 copepod nauplii ml⁻¹ compared to the mean of 5 rotifers ml⁻¹ that was used in our study. Heinle and Flemer (1975) reported a nauplius concentration of Eurytemora affinis Poppe 1880 as high as 2.8 individuals ml⁻¹ in Chesapeake Bay, which was quantified by Laurence (1977) to be more than adequate for growth and survival of P. americanus larvae. The lowest prey concentration that was used here was equal to 4.4 rotifers per ml. According to Hansen et al. (1994), nauplii and rotifers have a similar spherical diameter. Therefore, if one considers a size ratio of 1:1 between the two prey types, this further supports the hypothesis that food availability was not a limiting factor during the test. Moreover, since the present experiments were done under laboratory conditions, i.e., with an abundance of prey, clear and well-illuminated waters, and without competitors or predators, we provided optimal environmental conditions for efficient hunting. However, as pointed out by Purser and Radford (2011), the presence of noise in the natural environment is expected to have a greater impact on the species. For example, turbidity would affect hunting success since P. americanus are visual feeders, and the presence of predators would influence the foraging efficiency of larvae since distraction induced by boat noise may increase the risk of predation. Such hypotheses have been validated by Simpson et al. (2016), who showed that young Ambon damselfish *Pomacentrus amboinensis* exposed to boat noise responded less

 rapidly to simulated predatory attacks and were six times less likely to be startled by an attack compared with those tested in ambient conditions.

Kunc et al. (2014) exposed cuttlefish (*Sepia officinalis* L. 1758), a species that does not rely on acoustics for communication, to a noise playback of an underwater engine noise from a small car ferry. *S. officinalis* showed cross-modal impacts on both visual and tactile sensory modalities (Vermeij 2010; Kunc et al. 2014). Kunc et al. (2014) suggested that noise interference to one sort of sensory channel can affect performance in other sensory channels, thus considering each channel in isolation might lead to misinterpretation of the overall effect of noise pollution in the marine environment. Chan et al. (2010) also confirmed that multi-modal distractions reduce attention to biologically important tasks in the Caribbean hermit crab (*Coenobita clypeatus*). Such observations could be a result of the way sound propagates in water, since underwater acoustic stimuli consist of particle motion as well as sound pressure, both of which can provide information to individuals (Radford et al. 2014). Even though *P. americanus* larvae are visual feeders, the hypothesis of cross-modal impacts cannot be rejected.

Using juveniles and adults of different fish species, some studies have strongly suggested the presence of noise habituation. In a field study of juvenile damselfish *Pomacentrus amboinensis*, Holmes et al. (2017) showed that behaviour is altered in response to boat noise, but that the response is no longer present after 20 minutes of exposure, suggesting de-sensitization. In the Australian snapper *Pagrus auratus*, the behavioural response to motorboat sound was different whether observations were done inside or outside protected areas (Mensinger et al. 2018), and when comparing the

sensitivity of adult male cichlids (Cynotilapia zebroides) in zones characterized by different contrasting levels of motorboat disturbances in Lake Malawi, Harding et al. (2018) also concluded that the response level differed according to the "disturbance history". Habituation has also been suggested in 30 cm European sea bass *Dicentrarchus* labrax exposed to repeated impulsive sound (Neo et al. 2018). Could the effect of sound on feeding behaviour be different in winter flounder larvae in coastal environments due to habituation? What is the acclimation and the learning capacity at the larval stage, when energy is devoted to feeding to accumulating enough energy to undertake metamorphosis? Answering these questions will certainly require further investigation. P. americanus larvae metamorphose above 6.6 mm length (Vagner et al. 2013; Bélanger et al. 2018). Larvae are poorly developed before metamorphosis, and even though hearing ability has been detected as early as three days post-fertilization in other fish species (Simpson et al. 2005), no information is available on the hearing ability of *P. americanus* larvae. Do they respond to sound pressure changes or particle motion (Farkas et al. 2016)? We do not have the answers. However, P. americanus, like elasmobranchs and gobies, are among the fish that do not have a swim bladder. This species is therefore considered to possess a pure particle motion detector (Popper and Fay 2011). Future investigations are necessary to completely understand the impacts of noise on the larval stages of marine organisms.

Conclusion

The results of this study demonstrate that boat noise negatively affected the feeding behaviour of $t \stackrel{?}{E} \stackrel{?}{=} i \stackrel{?}{$

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Table 1. Sound levels (dB re 1μ Pa²) measured *in situ* from the vessel noise recorded during the three boat passages, before the experiment in the rearing aquaria, and during the experiment (mean \pm SEM for the four trials). There was no sound emission in aquaria 1 and 2; sound treatments were performed in aquaria 3 and 4.

100 - 1,000 Hz	1,000 - 10 000 Hz
130 ± 1	123 ± 2
86 ± 3	92 ± 2
100 ± 5	87 ± 6
108 ± 4	96 ± 5
104 ± 1	93 ± 1
122 ± 7	114 ± 8
119 ± 5	112 ± 8
	130 ± 1 86 ± 3 100 ± 5 108 ± 4 104 ± 1 122 ± 7

Fig. 1 Experimental set-up showing the dimensions (cm) and positions of aquaria containing larvae with the sound source in the water bath under the aquarium. Fig 2 Pseudopleuronectes americanus larva at the stage of development used in the present study. Fig. 3 Spectrum (dB re 1μPa² Hz⁻¹) of recorded sounds: boat noise recorded in situ (black line), in the two aquaria with sound treatment (blue lines), and in the two aquaria with no sound treatment (green lines). The gray shaded area corresponds to variations of natural ambient noise estimated from Wenz's formula for different wind (wind speeds from 0 to 10 m s⁻¹) and traffic (traffic density from 1 to 7) conditions. Fig. 4 Fork length (a) and eye diameter (b) of *Pseudopleuronectes americanus* larvae used in the different treatments (prey density: low, medium, high; boat noise: absent, present). Different letters indicate significantly different means among treatments (P < 0.05). Mean \pm S.D. Fig. 5 Mean number of hunts per 12 minutes per *Pseudopleuronectes americanus* larva (a), stomach volume (b) and percentage of time Pseudopleuronectes americanus larvae spent swimming stomach volume (c) in absence or presence of boat noise and fed with three different prey densities. Different letters indicate significantly different means among prey

- 631 densities. Significant sound effects are indicated on panels. No significant interactions
- between factors were present (see the Results section). Mean \pm s.D.

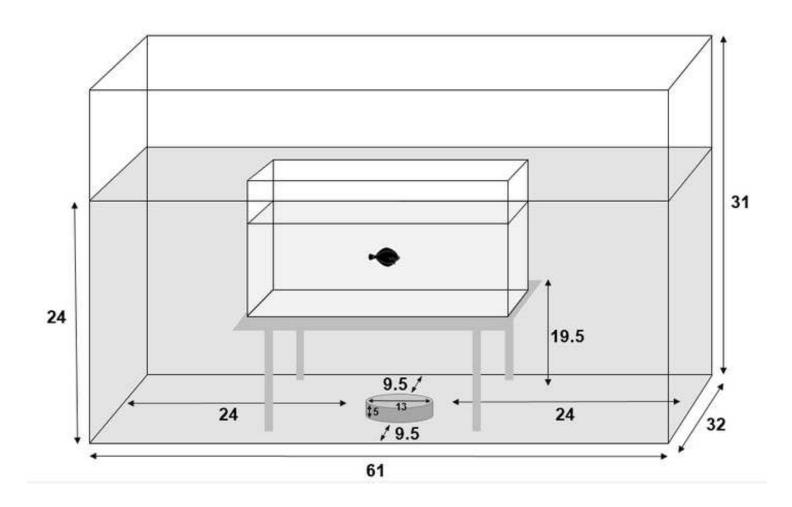


Figure 2

